Lecture 10: Recurrent Neural Networks

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"Vanilla" Neural Network

one to one



Vanilla Neural Networks

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e.g. Image Captioning image -> sequence of words

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sequence of video frames -> action class

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We can process a sequence of vectors **x** by applying a **recurrence formula** at every time step:



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We can process a sequence of vectors **x** by applying a **recurrence formula** at every time step:

$$h_t = f_W(h_{t-1}, x_t)$$

Notice: the same function and the same set of parameters are used at every time step.



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(Simple) Recurrent Neural Network

The state consists of a single *"hidden"* vector **h**:



Sometimes called a "Vanilla RNN" or an "Elman RNN" after Prof. Jeffrey Elman

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Re-use the same weight matrix at every time-step



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RNN: Computational Graph: Many to One



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RNN: Computational Graph: Many to One



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Sequence to Sequence: Many-to-one + one-to-many

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Many to one: Encode input sequence in a single vector



Sutskever et al, "Sequence to Sequence Learning with Neural Networks", NIPS 2014

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Sequence to Sequence: Many-to-one + one-to-many

One to many: Produce output sequence from single input vector



Sutskever et al, "Sequence to Sequence Learning with Neural Networks", NIPS 2014

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Vocabulary: [h,e,l,o]

Example training sequence: **"hello"**



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Example training sequence: **"hello"**

$$h_t = anh(W_{hh}h_{t-1}+W_{xh}x_t)$$



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Vocabulary: [h,e,l,o]

Example training sequence: **"hello"**



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Vocabulary: [h,e,l,o]

At test-time sample characters one at a time, feed back to model



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Vocabulary: [h,e,l,o]

At test-time sample characters one at a time, feed back to model



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Vocabulary: [h,e,l,o]

At test-time sample characters one at a time, feed back to model



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Vocabulary: [h,e,l,o]

At test-time sample characters one at a time, feed back to model



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Truncated Backpropagation through time



Run forward and backward through chunks of the sequence instead of whole sequence

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Truncated Backpropagation through time



Carry hidden states forward in time forever, but only backpropagate for some smaller number of steps

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Truncated Backpropagation through time



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THE SONNETS

by William Shakespeare

From fairest creatures we desire increase, That thereby beauty's rose might never die, But as the riper should by time decease, His tender heir might bear his memory: But thou, contracted to thine own bright eyes, Feed'st thy light's flame with self-substantial fuel, Making a famine where abundance lies, Thyself thy foe, to thy sweet self too cruel: Thou that art now the world's fresh ornament, And only herald to the gaudy spring, Within thine own bud buriest thy content, And tender churl mak'st waste in niggarding: Pity the world, or else this glutton be, To eat the world's due, by the grave and thee.

When forty winters shall besiege thy brow, And dig deep trenches in thy beauty's field, Thy youth's proud livery so gazed on now, Will be a tatter'd weed of small worth held: Then being asked, where all thy beauty lies, Where all the treasure of thy lusty days; To say, within thine own deep sunken eyes, Were an all-eating shame, and thriftless praise. How much more praise deserv'd thy beauty's use, If thou couldst answer This fair child of mine Shall sum my count, and make my old excuse,' Proving his beauty by succession thine! This were to be new made when thou art old, And see thy blood warm when thou feel'st it cold.



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at first:

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train more

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train more

Aftair fall unsuch that the hall for Prince Velzonski's that me of her hearly, and behs to so arwage fiving were to it beloge, pavu say falling misfort how, and Gogition is so overelical and ofter.

train more

"Why do what that day," replied Natasha, and wishing to himself the fact the princess, Princess Mary was easier, fed in had oftened him. Pierre aking his soul came to the packs and drove up his father-in-law women.

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```
static void do command(struct seg file *m, void *v)
{
  int column = 32 << (cmd[2] & 0x80);</pre>
 if (state)
    cmd = (int)(int state ^ (in 8(&ch->ch flags) & Cmd) ? 2 : 1);
 else
    seq = 1;
  for (i = 0; i < 16; i++) {</pre>
    if (k & (1 << 1))
      pipe = (in use & UMXTHREAD UNCCA) +
        ((count & 0x0000000fffffff8) & 0x000000f) << 8;
    if (count == 0)
      sub(pid, ppc md.kexec handle, 0x2000000);
    pipe set bytes(i, 0);
  /* Free our user pages pointer to place camera if all dash */
  subsystem info = &of changes[PAGE SIZE];
  rek controls(offset, idx, &soffset);
  /* Now we want to deliberately put it to device */
 control check polarity(&context, val, 0);
  for (i = 0; i < COUNTER; i++)</pre>
```

```
seq_puts(s, "policy ");
```

}

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Generated

C code



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quote detection cell

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Cell sensitive to position in line:

The sole importance of the crossing of the Bere zina that it plainly and indubitably proved the fallacy of all the plans for cutting off the enemy's retreat and the soundness of the only possible line of action--the one Kutuzov and the general mass of the army demanded -- namely, simply to follow the enemy up. The French crowd fled a continually increasing speed and all its energy was directed to reaching its goal. It fled like a wounded animal and it impossible was to block its path. This was shown not so much by the arrangements made for crossing as by what took place at the bridges. When the bridges broke down, unarmed soldiers, people from Moscow and women with children o were with the French transport, all--carried on by vis inertiae-pressed forward into boats and into the ice-covered water and did not, surrender.

line length tracking cell

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Cell that turns on inside comments and quotes:

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code depth cell

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RNN tradeoffs

RNN Advantages:

- Can process any length input
- Computation for step t can (in theory) use information from many steps back
- Model size doesn't increase for longer input
- Same weights applied on every timestep, so there is symmetry in how inputs are processed.

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RNN Disadvantages:

- Recurrent computation is slow
- In practice, difficult to access information from many steps back

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Image Captioning



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Explain Images with Multimodal Recurrent Neural Networks, Mao et al.

Deep Visual-Semantic Alignments for Generating Image Descriptions, Karpathy and Fei-Fei

Show and Tell: A Neural Image Caption Generator, Vinyals et al.

Long-term Recurrent Convolutional Networks for Visual Recognition and Description, Donahue et al.

Learning a Recurrent Visual Representation for Image Caption Generation, Chen and Zitnick

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Recurrent Neural Network



Convolutional Neural Network

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FC-1000 softmax

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FC-4096 FC 1090 softwax

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h = tanh(
$$W_{xh}$$
 * x + W_{hh} * h)
now:

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F

Lecture 10 -







F

Lecture 10 -



Image Captioning: Example Results

Captions generated using <u>neuraltalk2</u> All images are<u>CC0 Public domain:</u> <u>cat suitcase, cat tree, dog, bear,</u> <u>surfers, tennis, giraffe, motorcycle</u>





A cat sitting on a suitcase on the floor

A cat is sitting on a tree branch



A dog is running in the grass with a frisbee



A white teddy bear sitting in the grass



Two people walking on the beach with surfboards



A tennis player in action on the court



Two giraffes standing in a grassy field



A man riding a dirt bike on a dirt track

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Image Captioning: Failure Cases



A woman is holding a cat in her hand



A person holding a computer mouse on a desk



A woman standing on a beach holding a surfboard



A bird is perched on a tree branch



A man in a baseball uniform throwing a ball

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RNN focuses its attention at a different spatial location when generating each word



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Xu et al, "Show, Attend, and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

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Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

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Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

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Image Captioning with Attention



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Image Captioning with Attention



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Image Captioning with Attention



A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



A <u>stop</u> sign is on a road with a mountain in the background.



A little <u>girl</u> sitting on a bed with a teddy bear.



A group of <u>people</u> sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

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Visual Question Answering (VQA)



- Q: What endangered animal is featured on the truck?
- A: A bald eagle.
- A: A sparrow.
- A: A humming bird.
- A: A raven.



- Q: Where will the driver go if turning right?
- A: Onto 24 ³/₄ Rd. A: Onto 25 ³/₄ Rd.
- A: Onto 23 ³/₄ Rd.
- A: Unto 23 % Rd
- A: Onto Main Street.



- Q: When was the picture taken?
- A: During a wedding.
- A: During a bar mitzvah.
- A: During a funeral.
- A: During a Sunday church



- Q: Who is under the umbrella?
- A: Two women.
- A: A child.
- A: An old man.
- A: A husband and a wife.

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Agrawal et al, "VQA: Visual Question Answering", ICCV 2015 Zhu et al, "Visual 7W: Grounded Question Answering in Images", CVPR 2016 Figure from Zhu et al, copyright IEEE 2016. Reproduced for educational purposes.

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Visual Question Answering: RNNs with Attention



Zhu et al, "Visual 7W: Grounded Question Answering in Images", CVPR 2016 Figures from Zhu et al, copyright IEEE 2016. Reproduced for educational purposes.



What kind of animal is in the photo? A **cat**.



Why is the person holding a knife? To cut the **cake** with.

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Visual Dialog: Conversations about images



Das et al, "Visual Dialog", CVPR 2017 Figures from Das et al, copyright IEEE 2017. Reproduced with permission.

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Visual Language Navigation: Go to the living room

Agent encodes instructions in language and uses an RNN to generate a series of movements as the visual input changes after each move.

Wang et al, "Reinforced Cross-Modal Matching and Self-Supervised Imitation Learning for Vision-Language Navigation", CVPR 2018 Figures from Wang et al, copyright IEEE 2017. Reproduced with permission.

Instruction

Turn right and head towards the *kitchen*. Then turn left, pass a *table* and enter the *hallway*. Walk down the hallway and turn into the *entry way* to your right *without doors*. Stop in front of the *toilet*.



Initial Position Target Position

Demonstration Path A
 Executed Path B
 Executed Path C

Local visual scene



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All images are <u>CC0 Public domain</u>: dog,

Image Captioning: Gender Bias

Wrong



Baseline: A **man** sitting at a desk with a laptop computer. Right for the Right Reasons



Our Model: A **woman** sitting in front of a laptop computer. Right for the Wrong Reasons



Right for the Right Reasons



Baseline: A **man** holding a tennis racquet on a tennis court. Our Model: A **man** holding a tennis racquet on a tennis court.

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Burns et al. "Women also Snowboard: Overcoming Bias in Captioning Models" ECCV 2018 Figures from Burns et al, copyright 2018. Reproduced with permission.

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Visual Question Answering: Dataset Bias



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Jabri et al. "Revisiting Visual Question Answering Baselines" ECCV 2016

Multilayer RNNs



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Long Short Term Memory (LSTM)

Vanilla RNN

LSTM

$$h_t = \tanh\left(W\begin{pmatrix}h_{t-1}\\x_t\end{pmatrix}\right)$$

$$\begin{pmatrix} i \\ f \\ o \\ g \end{pmatrix} = \begin{pmatrix} \sigma \\ \sigma \\ \sigma \\ \tanh \end{pmatrix} W \begin{pmatrix} h_{t-1} \\ x_t \end{pmatrix}$$

$$c_t = f \odot c_{t-1} + i \odot g$$

$$h_t = o \odot \tanh(c_t)$$

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Hochreiter and Schmidhuber, "Long Short Term Memory", Neural Computation 1997

Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013



$$h_{t} = \tanh(W_{hh}h_{t-1} + W_{xh}x_{t})$$
$$= \tanh\left(\left(W_{hh} \quad W_{hx}\right) \begin{pmatrix}h_{t-1}\\x_{t}\end{pmatrix}\right)$$
$$= \tanh\left(W\begin{pmatrix}h_{t-1}\\x_{t}\end{pmatrix}\right)$$

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y_t

Backpropagation from h_t to h_{t-1} multiplies by W (actually W_{hh}^{T})



Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

$$h_{t} = \tanh(W_{hh}h_{t-1} + W_{xh}x_{t})$$
$$= \tanh\left(\left(W_{hh} \quad W_{hx}\right) \begin{pmatrix}h_{t-1}\\x_{t}\end{pmatrix}\right)$$
$$= \tanh\left(W\begin{pmatrix}h_{t-1}\\x_{t}\end{pmatrix}\right)$$

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Backpropagation from h, to h_{t-1} multiplies by W (actually W_{hh}^{T}) tanh h_{t-1} stack n. Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

$$h_{t} = \tanh(W_{hh}h_{t-1} + W_{xh}x_{t})$$
$$= \tanh\left(\left(W_{hh} \quad W_{hx}\right) \begin{pmatrix}h_{t-1}\\x_{t}\end{pmatrix}\right)$$
$$= \tanh\left(W\begin{pmatrix}h_{t-1}\\x_{t}\end{pmatrix}\right)$$

$$rac{\partial h_t}{\partial h_{t-1}} = tanh'(W_{hh}h_{t-1}+W_{xh}x_t)W_{hh}$$

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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013



$$rac{\partial L}{\partial W} = \sum_{t=1}^T rac{\partial L_t}{\partial W}$$

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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

Gradients over multiple time steps:



$$\frac{\partial L}{\partial W} = \sum_{t=1}^{T} \frac{\partial L_t}{\partial W}$$
$$\frac{\partial L_T}{\partial W} = \frac{\partial L_T}{\partial h_T} \frac{\partial h_t}{\partial h_{t-1}} \dots \frac{\partial h_t}{\partial W}$$

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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

Gradients over multiple time steps:



$$rac{\partial L}{\partial W} = \sum_{t=1}^T rac{\partial L_t}{\partial W}$$

$$rac{\partial L_T}{\partial W} = rac{\partial L_T}{\partial h_T} rac{\partial h_t}{\partial h_{t-1}} \dots rac{\partial h_1}{\partial W} = rac{\partial L_T}{\partial h_T} (\prod_{t=2}^T rac{\partial h_t}{\partial h_{t-1}}) rac{\partial h_1}{\partial W}$$

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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

Gradients over multiple time steps:



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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

Gradients over multiple time steps:



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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

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Gradients over multiple time steps:



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 $rac{\partial L}{\partial W} = \sum_{t=1}^T rac{\partial L_t}{\partial W}$ What if we assumed no non-linearity?

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Gradients over multiple time steps:



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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

Gradients over multiple time steps:



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Bengio et al, "Learning long-term dependencies with gradient descent is difficult", IEEE Transactions on Neural Networks, 1994 Pascanu et al, "On the difficulty of training recurrent neural networks", ICML 2013

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Gradients over multiple time steps:



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Long Short Term Memory (LSTM)

Vanilla RNN

LSTM

$$h_t = \tanh\left(W\begin{pmatrix}h_{t-1}\\x_t\end{pmatrix}\right)$$

$$\begin{pmatrix} i \\ f \\ o \\ g \end{pmatrix} = \begin{pmatrix} \sigma \\ \sigma \\ \sigma \\ \tanh \end{pmatrix} W \begin{pmatrix} h_{t-1} \\ x_t \end{pmatrix}$$

$$c_t = f \odot c_{t-1} + i \odot g$$

$$h_t = o \odot \tanh(c_t)$$

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Hochreiter and Schmidhuber, "Long Short Term Memory", Neural Computation 1997

Long Short Term Memory (LSTM) [Hochreiter et al., 1997]



- i: Input gate, whether to write to cell
- f: Forget gate, Whether to erase cell
- o: Output gate, How much to reveal cell
- g: Gate gate (?), How much to write to cell



$$c_t = f \odot c_{t-1} + i \odot g$$
$$h_t = o \odot \tanh(c_t)$$

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Long Short Term Memory (LSTM) [Hochreiter et al., 1997]



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Long Short Term Memory (LSTM): Gradient Flow [Hochreiter et al., 1997]



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Long Short Term Memory (LSTM): Gradient Flow [Hochreiter et al., 1997]

Uninterrupted gradient flow!



Notice that the gradient contains the f gate's vector of activations

- allows better control of gradients values, using suitable parameter updates of the forget gate.

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Also notice that are added through the **f**, **i**, **g**, and **o** gates

better balancing of gradient values

Do LSTMs solve the vanishing gradient problem?

The LSTM architecture makes it easier for the RNN to preserve information over many timesteps

- e.g. if the f = 1 and the i = 0, then the information of that cell is preserved indefinitely.
- By contrast, it's harder for vanilla RNN to learn a recurrent weight matrix Wh that preserves info in hidden state •

LSTM doesn't guarantee that there is no vanishing/exploding gradient, but it does provide an easier way for the model to learn long-distance dependencies

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Long Short Term Memory (LSTM): Gradient Flow [Hochreiter et al., 1997]

Uninterrupted gradient flow!



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Long Short Term Memory (LSTM): Gradient Flow [Hochreiter et al., 1997]

Uninterrupted gradient flow!



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Other RNN Variants

GRU [*Learning phrase representations using rnn encoder-decoder for statistical machine translation*, Cho et al. 2014]

$$r_t = \sigma(W_{xr}x_t + W_{hr}h_{t-1} + b_r)$$

$$z_t = \sigma(W_{xz}x_t + W_{hz}h_{t-1} + b_z)$$

$$\tilde{h}_t = \tanh(W_{xh}x_t + W_{hh}(r_t \odot h_{t-1}) + b_h)$$

$$h_t = z_t \odot h_{t-1} + (1 - z_t) \odot \tilde{h}_t$$

[LSTM: A Search Space Odyssey, Greff et al., 2015] [An Empirical Exploration of Recurrent Network Architectures, Jozefowicz et al., 2015]

MUT1:

$$z = \operatorname{sigm}(W_{xx}x_t + b_x)$$

$$r = \operatorname{sigm}(W_{xr}x_t + W_{hr}h_t + b_r)$$

$$h_{t+1} = \operatorname{tanh}(W_{hh}(r \odot h_t) + \operatorname{tanh}(x_t) + b_h) \odot z$$

$$+ h_t \odot (1 - z)$$

MUT2:

 $\begin{array}{lll} z &=& \mathrm{sigm}(W_{\mathrm{xx}}x_t+W_{\mathrm{hx}}h_t+b_{\mathrm{z}})\\ r &=& \mathrm{sigm}(x_t+W_{\mathrm{hr}}h_t+b_{\mathrm{r}})\\ h_{t+1} &=& \mathrm{tanh}(W_{\mathrm{hh}}(r\odot h_t)+W_{xh}x_t+b_{\mathrm{h}})\odot z\\ &+& h_t\odot(1-z) \end{array}$

MUT3:

$$z = \operatorname{sigm}(W_{xx}x_t + W_{hx}\tanh(h_t) + b_z)$$

$$r = \operatorname{sigm}(W_{xr}x_t + W_{hr}h_t + b_r)$$

$$h_{t+1} = \operatorname{tanh}(W_{hh}(r \odot h_t) + W_{xh}x_t + b_h) \odot z$$

$$+ h_t \odot (1 - z)$$

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Recently in Natural Language Processing... New paradigms for reasoning over sequences

["Attention is all you need", Vaswani et al., 2018]

- New "Transformer" architecture no longer processes inputs sequentially; instead it can operate over inputs in a sequence in parallel through an attention mechanism
- Has led to many state-of-the-art results and pre-training in NLP, for more interest see e.g.
 - "BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding", Devlin et al., 2018
 - OpenAl GPT-2, Radford et al., 2018



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Summary

- RNNs allow a lot of flexibility in architecture design
- Vanilla RNNs are simple but don't work very well
- Common to use LSTM or GRU: their additive interactions improve gradient flow
- Backward flow of gradients in RNN can explode or vanish.
 Exploding is controlled with gradient clipping. Vanishing is controlled with additive interactions (LSTM)
- Better/simpler architectures are a hot topic of current research, as well as new paradigms for reasoning over sequences
- Better understanding (both theoretical and empirical) is needed.

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